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Sato

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(54) **ROBOT SYSTEM FOR PERFORMING
FORCE CONTROL**

(71) Applicant: **FANUC Corporation**, Yamanashi (JP)

(72) Inventor: **Takashi Sato**, Yamanashi (JP)

(73) Assignee: **FANUC CORPORATION**, Yamanashi
(JP)

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CPC **B25J 11/005** (2013.01); **B25J 13/085**
(2013.01); **B25J 13/088** (2013.01); **Y10S**
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(58) **Field of Classification Search**

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See application file for complete search history.

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Primary Examiner — Harry Oh

(74) *Attorney, Agent, or Firm* — Hauptman Ham, LLP

(57)

ABSTRACT

A robot system includes a robot that operates to move a machining tool relative to a workpiece, an actuator that changes a position of the machining tool, and a control device that controls the robot. The control device includes a robot control unit that operates the robot along a predetermined motion trajectory, a force detection unit that detects force acting between the machining tool and the workpiece, a position detection unit that detects a current position of the machining tool, a force control unit that obtains a target position of the machining tool such that a detection value of the force detection unit approaches a predetermined value, and a position correction unit that calculates a position correction amount of a motion trajectory of the robot and a position correction amount of the actuator in response to the target position of the machining tool.

9 Claims, 8 Drawing Sheets

